# GRIFEX

GEO-CAPE ROIC In-Flight
Experiment

**Jet Propulsion Laboratory** 

D. Rider 23 June 2015

Advanced imaging technology enabling atmospheric chemistry and pollution transport science from GEO



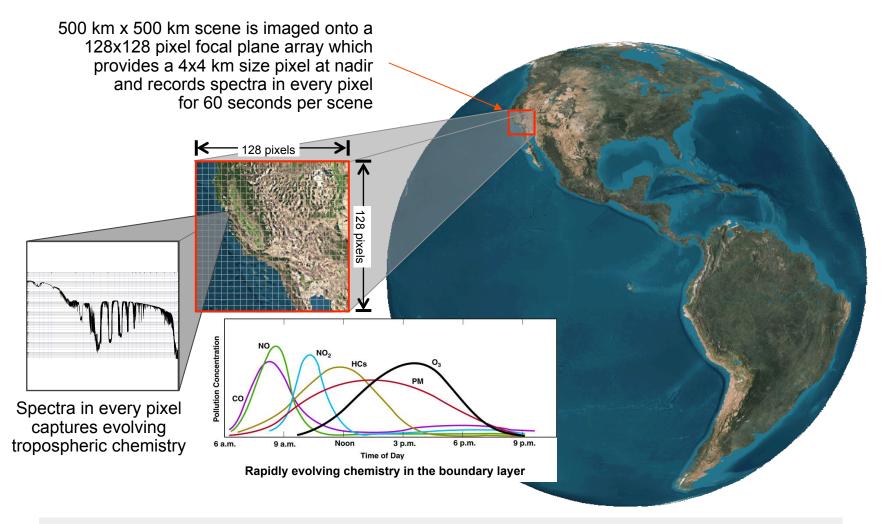






# Geostationary Orbit Observing Scenario





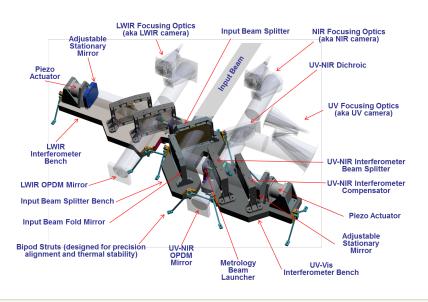
From geostationary orbit PanFTS can map all of North and South America hourly with high resolution measurements (temporal, spatial, and spectral) that capture rapidly evolving tropospheric chemistry with planetary boundary layer sensitivity



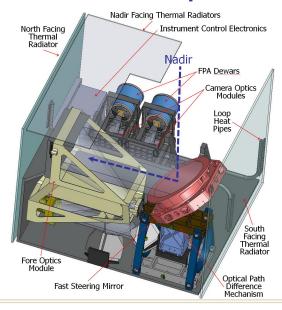
## **PanFTS Instrument Concept**



#### PanFTS EM



#### **GCPI Concept**

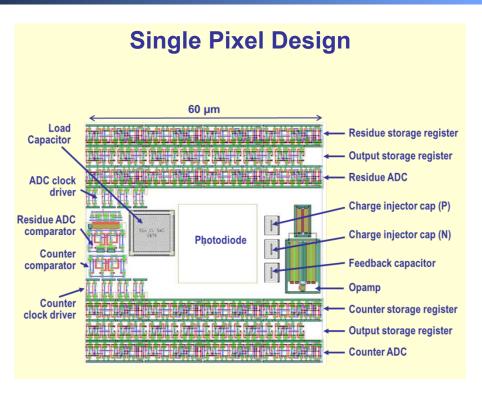


- High spectral resolution (0.06 cm<sup>-1</sup>) and wide spectral sensitivity (15 to 0.26 🗑 m) allows simultaneous measurement of reflected sunlight and thermal emission (day and night) enabling retrieval of several important atmospheric composition species such as Pollutants (O<sub>3</sub>, NO<sub>2</sub>, NH<sub>3</sub>, SO<sub>2</sub>, HCHO, CH<sub>3</sub>OH, CO), Greenhouse Gases (CO<sub>2</sub>, CH<sub>4</sub>, N<sub>2</sub>O, O<sub>3</sub>, H<sub>2</sub>O), and Transport Tracers (HDO, N<sub>2</sub>O, O<sub>2</sub>, O<sub>4</sub>)
- The PanFTS design has two separate channels optimized for the infrared and Vis spectral domains, and multiple high speed focal
  plane arrays (FPAs) which simultaneously capture high-precision interferograms in each pixel for all of the wavelengths in the
  spectral range
- The UV-Vis side of the interferometer is based on the Fourier Transform UV Spectrometer (FTUVS) which has been operating for over 12 years at the Table Mountain Facility
- The overall design is compact because the two channels share a common fore optics, and a single common interferometer optical path difference mechanism (OPDM)

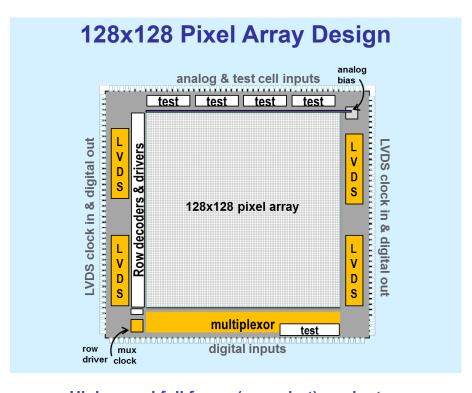


### **ROIC Design**





- High readout rate (12 kHz)
- High resolution readout (14 bits)
- Mixed analog/digital signal circuit elements
- Pixel footprint size limited to 60 μm
- Low power draw at full speed
- Design for testability



- High speed full frame (snapshot) readout
- Robust power distribution and signal flow
- Layout that minimizes pixel-to-pixel crosstalk
- Minimal sensitivity to manufacturing limitations
- Low power draw (slow clock rates)
- Design for testability and hybridization

In-Pixel digitization ROIC encompasses two tightly coupled design challenges: (1) pixel design, and (2) array design

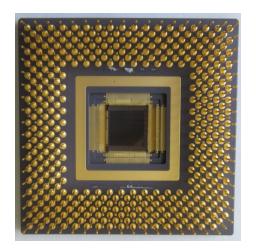


#### **High Speed Imaging Demonstration**



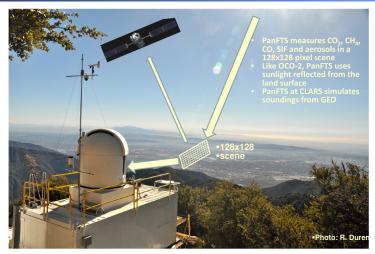


- Designed and fabricated the 128 X 128 ROIC in 180 nm CMOS
- Innovative in-pixel digitization ROIC has been developed that enables all digital FPAs (photons in produces bits out proportional to the intensity of the incident light)
- First run success developing brand new, unique ROIC design and fabrication
- Stop action experiment demonstrated ROIC capability for the high speed imaging needed to make rapid measurements
- Overall ROIC performance is outstanding and can be improved with array design refinements

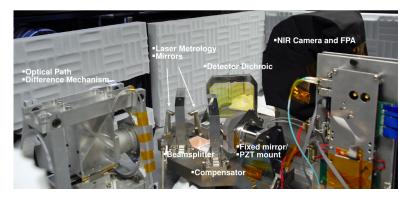




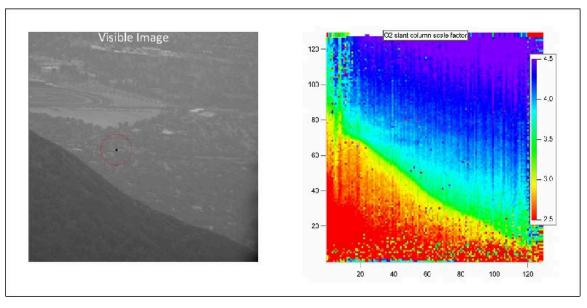
#### **GRIFEX Detector In CLARS PanFTS**



PanFTS Viewing Geometry at CLARS



PanFTS Interferometer at CLARS



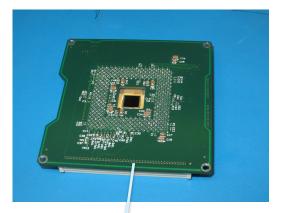
Visible image (L) and retrieved O<sub>2</sub> image spectra acquired with GIFEX detector



#### The GRIFEX CubeSat Camera



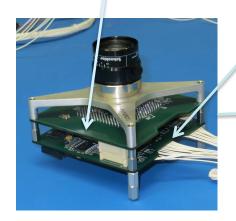
#### **GRIFEX Detector Board**



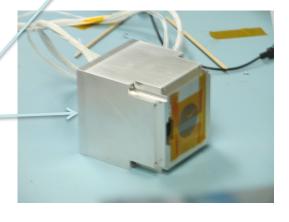
#### Camera Controller Board



- ROIC hybridized to Raytheon Vision Systems Si PIN photo diode array
- All electronic parts are commercial off the shelf (i.e. Digilab)
- Optic is a ruggedized commercial lens
- The camera runs at 8 kHz frame rate
- Controller was derived from the M<sup>3</sup>
   CubeSat design and buffers 150
   frames of camera data.



Built-up Camera



1-U GRIFEX Camera Al Housing



## **GRIFEX Spacecraft**





A few of the very many University of Michigan MXL students who worked on GRIFEX

The 3-U GRIFEX CubeSat was designed, built, tested and integrated by the students of the Michigan Exploration Laboratory (MXL):

- 10 cm x 10 cm x 30 cm, 3 kg and ~6 W
- Magnetic field attitude stabilized

MXL is also doing all operations too.

Launched on as an auxiliary payload aboard the SMAP launch vehicle on January 31, 2015

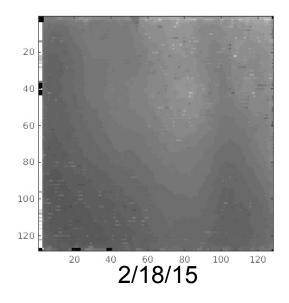
Lunch vehicle integration was managed by the Educational Launch of Nanosatellites program (Kennedy and CalPoly SLO)

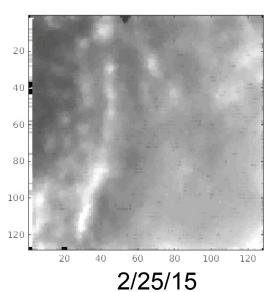
In an approximately 650 km circular orbit with 6 am/6 pm equator crossing time and 95 minute orbit period

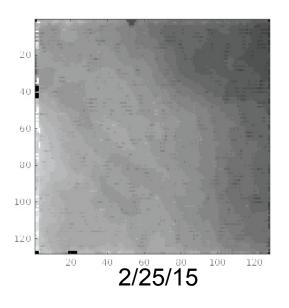


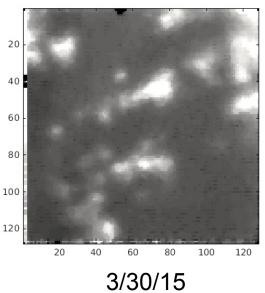
## **A Few GRIFEX Images**













## Summary



- Innovative in-pixel digitization ROIC/Detector has been developed that enables all digital FPAs
   (photons in produces bits out proportional to the intensity of the incident light)
- Took 3 ½ years to build and launch longer than originally planned
- Many more people contributed to the effort than originally thought.
  - Over 120 individuals made notable contributions. JPL, University of Michigan, Raytheon Vision Systems, Cal Poly San Luis Obispo, Kennedy Launch Services and Ham Radio Operators
- Collecting data is a bit slower than anticipated
  - S/C magnetic attitude stabilization is more is not quite as deterministic as inticipated
- The Spacecraft and the GRIFEX detector continue to operate normally and we anticipate many more months active operation and data collection.
- Demonstrated that the GRIFEX ROIC/Detector performs very well in the space environment.